



Filippo Bertoncelli

has been awarded an

Honorable Mention

as one of the finalist papers

for the Young Author Award

at the 10th IFAC Symposium on Intelligent Autonomous Vehicles IAV 2019

in Gdańsk, Poland



for the paper entitled

Wheel Slip Avoidance through a Nonlinear Model Predictive Control for Object Pushing with a Mobile Robot

co-authored by

Fabio Ruggiero, Lorenzo Sabattini

and presented by

Filippo Bertoncelli from University of Modena and Reggio Emilia

Young Author Award Finalist